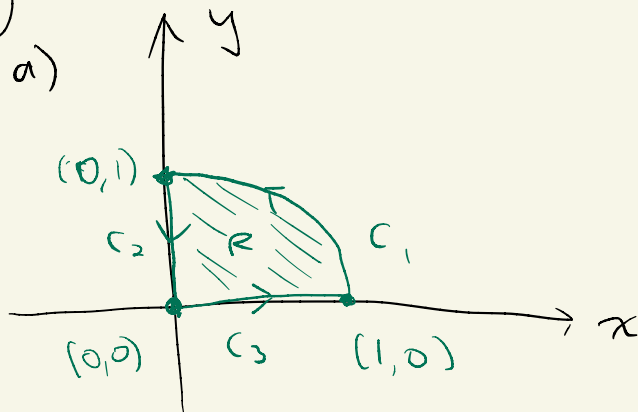


①

a)



b) Use the curl/component test:

$$\text{curl } \vec{F} = \hat{k} \left(\frac{\partial}{\partial y}(y) - \frac{\partial}{\partial x}(x) \right)$$

$$= \hat{k} (1 - 1)$$

$$= \vec{0}$$

$\vec{F} \rightarrow \text{conservative}$

$$\text{curl } \vec{G} = \hat{k} \left(\frac{\partial}{\partial y}(-y) - \frac{\partial}{\partial x}(x) \right)$$

$$= -2\hat{k}$$

$$\neq \vec{0}$$

$\vec{G} \rightarrow \text{not conservative}$

1c) i)

$$\oint_C (\vec{F} + \vec{G}) \cdot d\vec{r} = \oint_C \vec{F} \cdot d\vec{r} + \oint_C \vec{G} \cdot d\vec{r}$$

0 since $\vec{F}$ conservative

$$= \oint_C \vec{G} \cdot d\vec{r}$$

$$= \int_{C_1} \vec{G} \cdot d\vec{r} + \int_{C_2} \vec{G} \cdot d\vec{r} + \int_{C_3} \vec{G} \cdot d\vec{r}$$

$$\cdot \int_{C_1} \vec{G} \cdot d\vec{r} = \int_{t=0}^{t=\pi} (-\sin t \hat{i} + \cos t \hat{j}) \cdot (-\sin t \hat{i} + \cos t \hat{j}) dt$$

" $\vec{r}'(t)$ "

parametrize

by $\vec{r}(t) = \cos t \hat{i} + \sin t \hat{j}$
 $0 \leq t \leq 2\pi$

$$= \int_0^{2\pi} \sin^2 t + \cos^2 t \, dt$$

$$= \frac{\pi}{2}$$

1c) i), cont.

$$\begin{aligned} \int_{C_2} \vec{G} \cdot d\vec{r} &= \int_{C_2} M dx + N dy \\ &= \int_0^1 M(0) + N(-dt) \\ &= \int_0^1 x(-dt) \\ &= \int_0^1 (0) dt \\ &= 0 \end{aligned}$$

parametrize

$$\begin{aligned} x &= 0 \\ dx &= 0 \\ y &= 1-t \\ dy &= -dt \\ 0 &\leq t \leq 1 \end{aligned}$$

$$\begin{aligned} \int_{C_3} \vec{G} \cdot d\vec{r} &= \int_{C_3} M dx + N dy \\ &= \int_0^1 -0 \cdot dt + x \cdot 0 \\ &= 0 \end{aligned}$$

$$\begin{aligned} x &= t \\ dx &= dt \\ y &= 0 \\ dy &= 0 \\ 0 &\leq t \leq 1 \end{aligned}$$

$$\Rightarrow \boxed{\oint_C \vec{G} \cdot d\vec{r} = \frac{\pi}{2} + 0 + 0 = \frac{\pi}{2}}$$

1c) ii)

$\vec{F}$ is conservative

$$\oint_C (\vec{F} - \vec{G}) \cdot d\vec{r} = \oint_C \vec{F} \cdot d\vec{r} - \oint_C \vec{G} \cdot d\vec{r}$$

$$= - \oint_C \vec{G} \cdot d\vec{r}$$

From
part i)

$$= - \frac{\pi}{2}$$

i) d) i)

$$\oint_C (\vec{F} + \vec{G}) \cdot \vec{n} \, ds$$

$$= \iint_R \nabla \cdot (\vec{F} + \vec{G}) \, dA$$

divergence
Theorem

$$\nabla \cdot \vec{F} = \frac{\partial}{\partial x} y + \frac{\partial}{\partial y} x = 0$$

$$\nabla \cdot \vec{G} = \frac{\partial}{\partial x} (-y) + \frac{\partial}{\partial y} x = 0$$

$$= \iint_R \nabla \cdot \vec{F} + \nabla \cdot \vec{G} \, dA$$

$$= \iint_R 0 + 0 \, dA$$

$$\boxed{= 0}$$

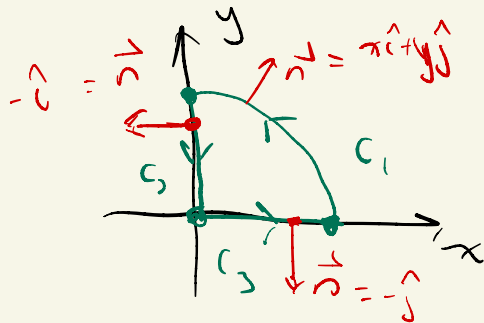
divergence theorem

$$ii) \oint_C (\vec{F} - \pi \vec{G}) \cdot \vec{n} \, ds = \iint_R \nabla \cdot (\vec{F} - \pi \vec{G}) \, dA$$

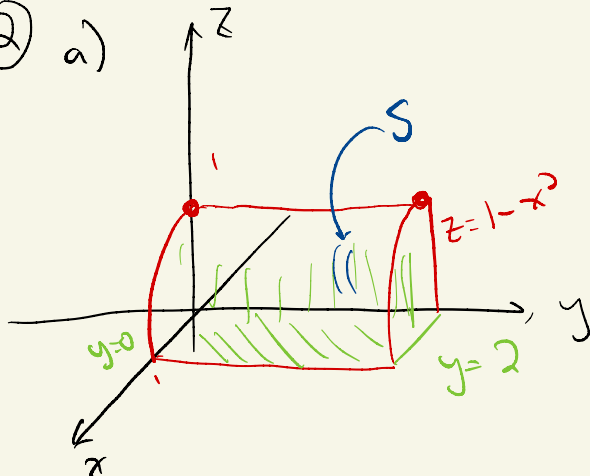
$$\text{linearity} \rightarrow = \iint_R \nabla \cdot \vec{F} - \pi \nabla \cdot \vec{G} \, dA$$

$$= \iint_R 0 - 0 \, dA$$

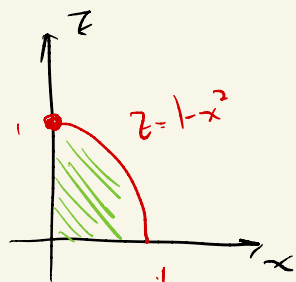
$$\boxed{= 0}$$



② a)



side view:



b) i)

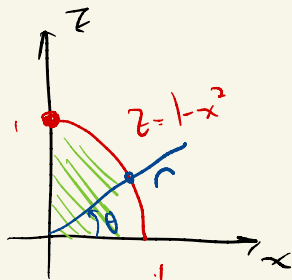
$$\int_{x=0}^1 \int_{y=0}^2 \int_{z=0}^{1-x^2} f(x,y,z) dz dy dx$$

$$= \int_0^1 \int_0^2 \int_0^{1-x^2} f(x,y,z) dz dy dx$$

ii)

$$\begin{aligned} x &= r \cos \theta \\ y &= y \\ z &= r \sin \theta \end{aligned}$$

$$\int_{y=0}^2 \int_{\theta=0}^{\frac{\pi}{2}} \int_{r=0}^1 f(r,\theta,y) r dr d\theta dy$$



$$= \int_0^2 \int_0^{\frac{\pi}{2}} \int_0^1 f(r,\theta,y) r dr d\theta dy$$

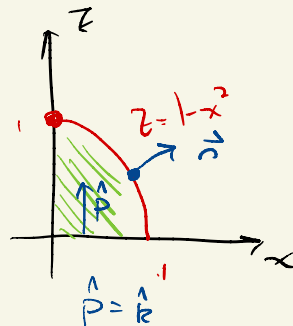
c) Let's use implicit method to compute this.

$$\text{Let } F(x, y, z) = x^2 + z$$

$$\Rightarrow S \text{ is the level surface } F(x, y, z) = 1$$

$$\begin{aligned} \vec{n} &= \pm \frac{\nabla F}{|\nabla F|} \\ &= \pm \frac{2x\hat{i} + \hat{k}}{\sqrt{4x^2 + 1}} \\ &\rightarrow \boxed{= \frac{2x\hat{i} + \hat{k}}{\sqrt{4x^2 + 1}}} \end{aligned}$$

to point outward, need +.



$$d\sigma = \frac{|\nabla F|}{|\nabla F \cdot \hat{p}|} dA$$

choose $\hat{p} = \hat{k}$

$$= \frac{\sqrt{4x^2 + 1}}{|(2x\hat{i} + \hat{k}) \cdot \hat{k}|} dA$$

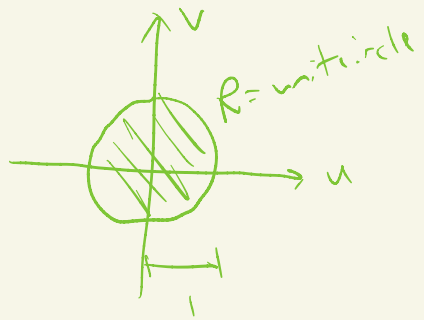
$$\boxed{= \sqrt{4x^2 + 1} dA}$$

③ a) Let

$$x = u$$

$$y = v$$

$$z = -\pi x - ey$$
$$= -\pi u - ev$$



$$\Rightarrow \boxed{\vec{r}(u, v) = u\hat{i} + v\hat{j} + (-\pi u - ev)\hat{k}}$$

$R = \text{unit disc in } (u, v)$

b) The unit normal to a plane
can be found by using

$$\pi x + ey + z = 0$$

$$\Rightarrow \vec{n} = \pm \frac{\langle \pi, e, 1 \rangle}{|\langle \pi, e, 1 \rangle|} = \pm \frac{\langle \pi, e, 1 \rangle}{\sqrt{\pi^2 + e^2 + 1}}$$

want it pointing down

$$\Rightarrow \text{want } \vec{n} \cdot \hat{k} < 0$$

$$\text{since } \vec{n} \cdot \hat{k} = \pm \frac{1}{\sqrt{\pi^2 + e^2 + 1}}, \text{ choose}$$

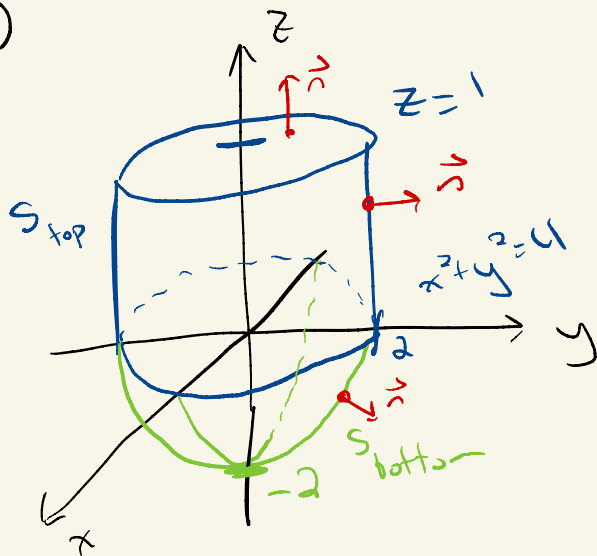
$$\boxed{\vec{n} = -\frac{\langle \pi, e, 1 \rangle}{\sqrt{\pi^2 + e^2 + 1}}}$$

3c) Let's use explicit form. $f(x,y) = z = -\pi x - ey$

$$\begin{aligned} d\sigma &= \sqrt{f_x^2 + f_y^2 + 1} \, dA \\ &= \sqrt{\pi^2 + e^2 + 1} \, dx dy \end{aligned}$$

$$\begin{aligned} \Rightarrow \text{Area} &= \iint_{\substack{\text{unit} \\ \text{disc}}} d\sigma \\ &= \iint_{\substack{\text{unit} \\ \text{disc}}} \sqrt{\pi^2 + e^2 + 1} \, dx dy \\ &= \sqrt{\pi^2 + e^2 + 1} \iint_{\substack{\text{unit} \\ \text{disc}}} dx dy \\ &= \sqrt{\pi^2 + e^2 + 1} \text{Area}(\text{unit disc}) \\ &= \sqrt{\pi^2 + e^2 + 1} (\pi) \end{aligned}$$

④ a)



b) Let's use the divergence theorem.

$$\oint_S \vec{F} \cdot \vec{n} d\sigma = \iiint_D \nabla \cdot \vec{F} dV$$

divergence
thm

$$= \iiint_D -1 -1 -1 dV$$

$$= -3 \iiint_D dV$$

$$= -3 (\text{Vol}(\text{cylinder}) + \text{Vol}(\text{half sphere}))$$

$$= -3 \left(\pi(2)^2(1) + \frac{4}{3} \pi(2)^2 \right)$$

$$= -12\pi - 16\pi$$

$$\boxed{= -28\pi}$$

4c) i) Note that

$$\iint_{S_{\text{top}}} \vec{G} \cdot \vec{n} d\sigma = \iint_{S_{\text{top}}} (\nabla \times \vec{H}) \cdot \vec{n} d\sigma$$

Stokes'
theorem

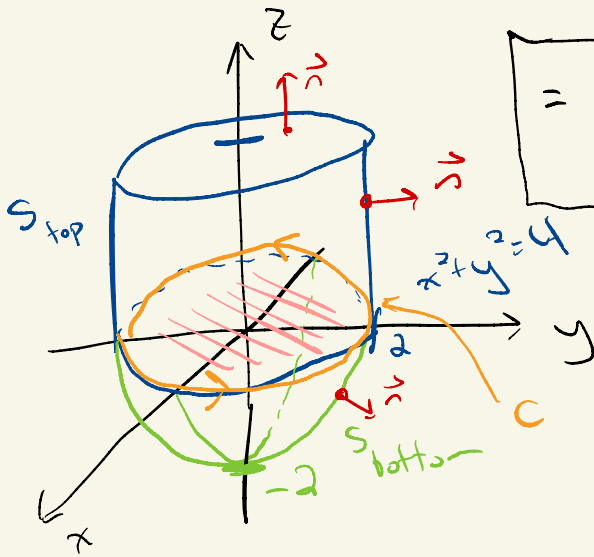
$$= \oint_C \vec{H} \cdot d\vec{r}$$

Stokes'
again

$$= \iint_{S_{\text{top}}} (\nabla \times \vec{H}) \cdot \vec{n} d\sigma$$

$\vec{I}$

$$= \int_0^{2\pi} \int_0^2 \vec{G} \cdot \hat{k} r dr d\theta$$



4c ii)

$$\vec{G} = \nabla \times \vec{H}$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -y & x & e^z \end{vmatrix}$$

$$= \hat{i}(0) - \hat{j}(0) + \hat{k}(1+1)$$

$$= 2\hat{k}$$

$$\iint_{S_{\text{top}}} \vec{G} \cdot \vec{n} d\sigma = \int_0^{2\pi} \int_0^2 \vec{G} \cdot \hat{k} r dr d\theta$$

i)

$$= \int_0^{2\pi} \int_0^2 2r dr d\theta$$

$$= 2 \int_0^{2\pi} \int_0^2 r dr d\theta$$

$$= 2 \text{ Area (radius 2 disk)}$$

$$= 2 \cdot 2^2 \pi$$

$$= 8\pi$$

4 c iii) $\iint_{S_{\text{bottom}}} \vec{G} \cdot \vec{n} \, d\sigma = \iint_{S_{\text{bottom}}} (\nabla \times \vec{A}) \cdot \vec{n} \, d\sigma$

Stokes $\rightarrow = \oint_C \vec{H} \cdot d\vec{r}$
 Careful with orientation! $\rightarrow$
 $= - \oint_C \vec{H} \cdot d\vec{r}$

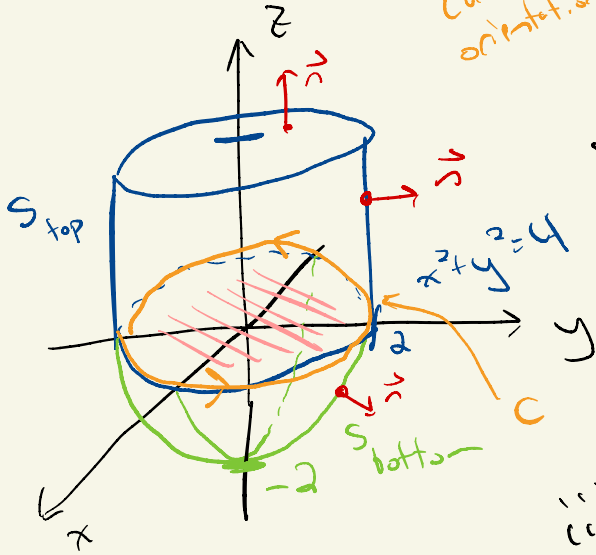
$$= - \oint_C \vec{A} \cdot d\vec{r}$$

stokas

$$L_2 = - \iint_{S_{\text{top}}} (\nabla \times \vec{A}) \cdot d\vec{\tau}$$

$$= - \iint_{S_{t.p}} \vec{G} \cdot \vec{n}$$

(ii) $\rightarrow$ $\boxed{= -8\pi}$



4d) "curl of gradient is 0"

$$\oint_S \underbrace{\left[\nabla \times (\nabla e^{i \arctan(x/y)}) \right]}_{=0} \cdot \vec{n} \, d\sigma$$

$$= 0$$

$$5) \text{ Let } u = x - 2$$

$$v = 2y$$

$$\Rightarrow x = u + 2$$

$$y = \frac{1}{2}v$$

$$\begin{aligned} \Rightarrow \det(J) &= \det \left(\begin{bmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{bmatrix} \right) \\ &= \det \left(\begin{bmatrix} 1 & 0 \\ 0 & \frac{1}{2} \end{bmatrix} \right) \\ &= \frac{1}{2} \end{aligned}$$

Bounds:

$$\begin{aligned} \bullet -\infty < x < \infty & \bullet -\infty < y < \infty \\ \bullet -\infty < x-2 < \infty & \bullet -\infty < 2y < \infty \end{aligned}$$

$$\text{So } -\infty < u < \infty \text{ and } -\infty < v < \infty$$

$$\begin{aligned} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-((x-2)^2 + (2y)^2)} dx dy &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-(u^2 + v^2)} \left(\frac{1}{2} \right) du dv \\ &= \frac{1}{2} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-(u^2 + v^2)} du dv \\ &= \boxed{\frac{\pi}{2}} \end{aligned}$$

(6)

a) False.

$$\int_a^b \underbrace{\vec{F} \cdot \vec{r}'(t)}_{\text{vector} \cdot \text{scalar} = \text{scalar}} dt$$

Only integrals of scalar functions
give scalars!

b) True. These are integrals that compute
arc length of C , which are independent of
parameterization.

c) True

By the fundamental theorem of
line integrals,

$$\oint_C \nabla f \cdot d\vec{r} = 0 \quad \text{for any loop } C$$

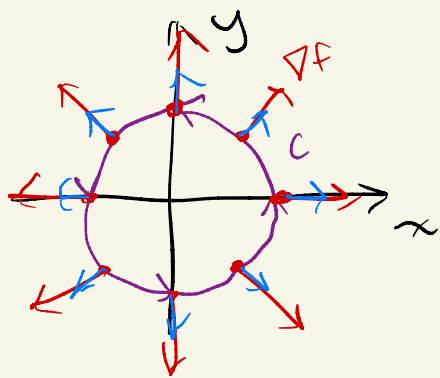
6 d) False. Here's a counterexample.

Suppose $f(x, y) = x^2 + y^2$ and suppose C is defined by $1 = x^2 + y^2$ (the unit circle).

Then

$$\nabla f = 2x\hat{i} + 2y\hat{j}$$

$$\vec{n} = x\hat{i} + y\hat{j}$$



$$\Rightarrow \oint_C \nabla f \cdot \vec{n} \, ds$$

$$= \oint_C 2(x^2 + y^2) \, ds$$

$$x^2 + y^2 = 1$$

$$= 2 \oint_C ds$$

$$= 2 \text{ length}(C)$$

$$> 0$$